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Debye sheath: comparison between fluid predictions & kinetic simulations

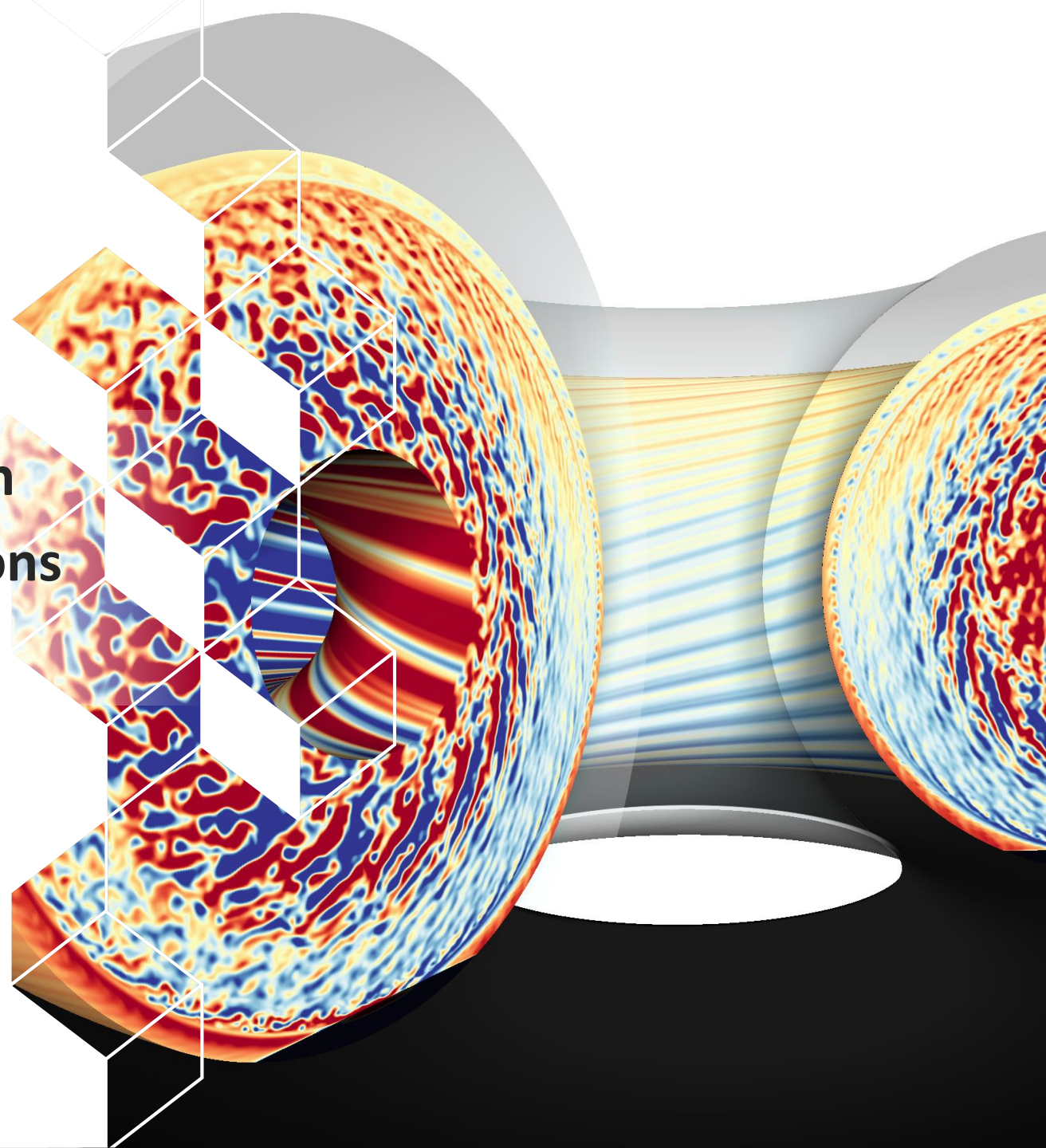
Towards a gyrokinetic modeling

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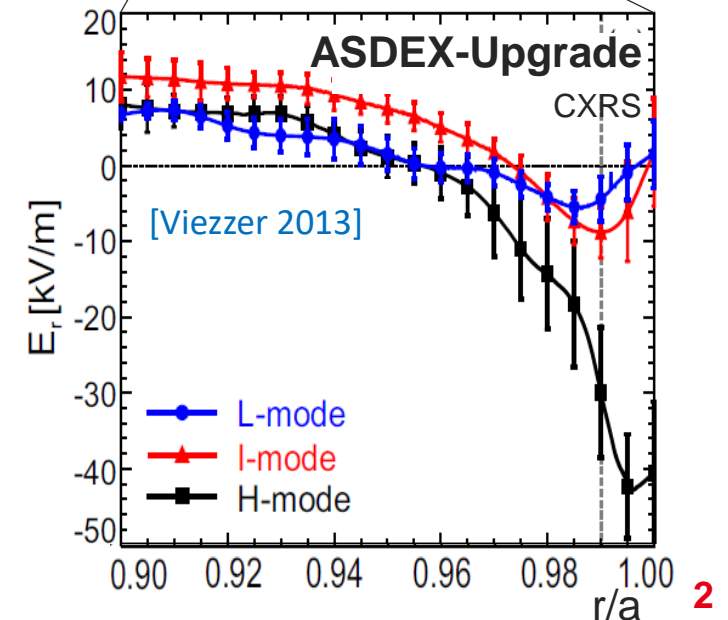
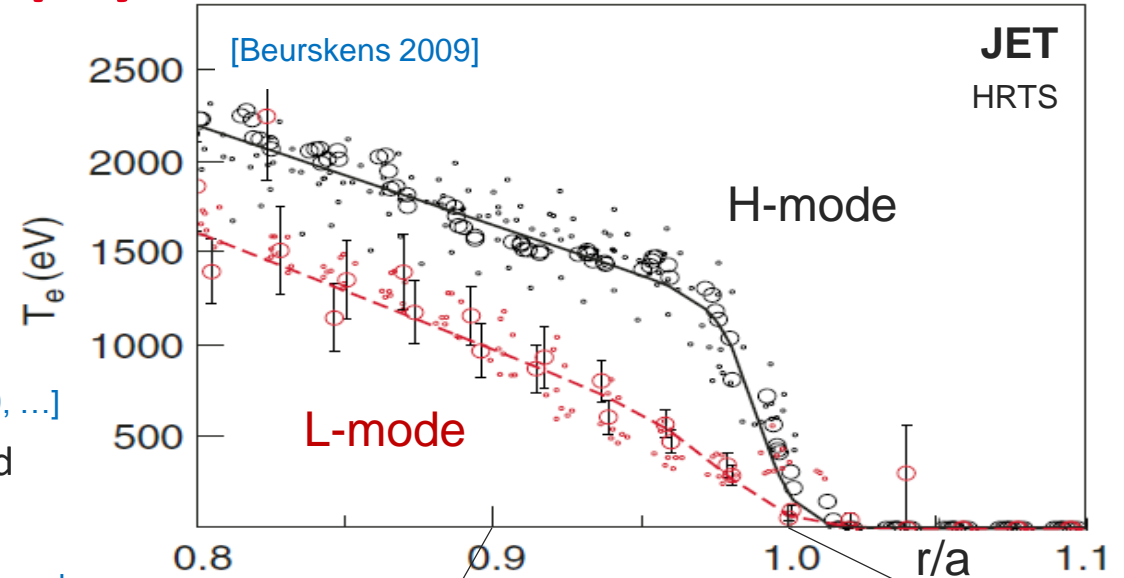


Physical context: improved confinement in tokamak plasmas largely governed by edge physics

- ❑ Energy confinement in tokamak plasmas governed by **turbulent transport** across magnetic field surfaces
- ❑ Most regimes of improved confinement characterized by **transport barriers** close to last closed field surface
- ❑ Critical role of the **sheared radial electric field E_r** (\rightarrow sheared rotation of turb. eddies) in turbulence regulation

[Wagner 1982, Whyte 2010, ...]

[Itoh-Itoh 1988, Biglari-Diamond-Terry 1990, ...]



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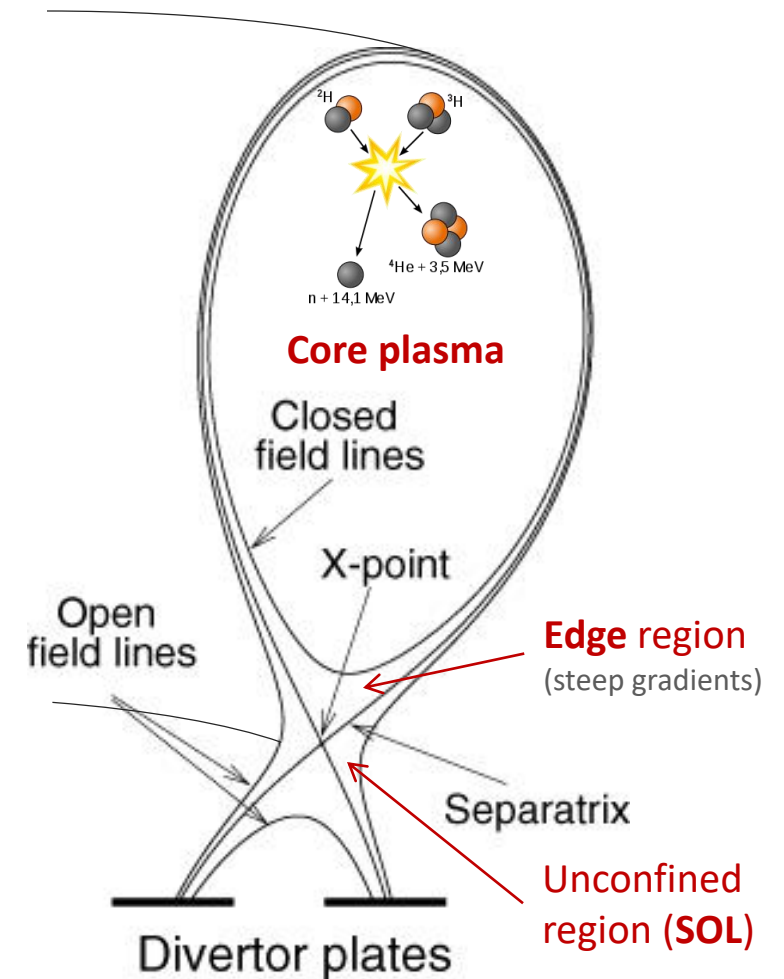
- ❑ Several players involved in **E_r profile:**

- *Confined region*: radial force balance
- *Edge*: ion orbit losses, collisional drag
- *SOL*: plasma-wall interaction
- *All*: turbulence (Reynolds stress)

[Itoh-Itoh 1988, Biglari-Diamond-Terry 1990, ...]

$$E_r = \frac{\nabla_r p_{\perp i}}{en} - V_{\theta} B_{\varphi} + V_{\varphi} B_{\theta}$$

$$E_r^{SOL} \approx -\frac{\Lambda}{e} \nabla_r T_e$$



Need for **core-edge-SOL modeling** to understand & predict bifurcations toward improved confinement regimes

Outline



- 1. Kinetics of plasma-wall interaction:** analogies with & departures from fluid predictions (VOICE)
2. Coupling kinetic plasma species & fluid neutrals – proof of principle (VOICE)
3. Towards the implementation of plasma-wall interaction in 5D gyrokinetics (GYSELA)

VOICE = (1D,1V) – fully kinetic electrons & ions – Poisson

GYSELA = (3D,2V) – GK ions, DK electrons – Quasi-Neutrality

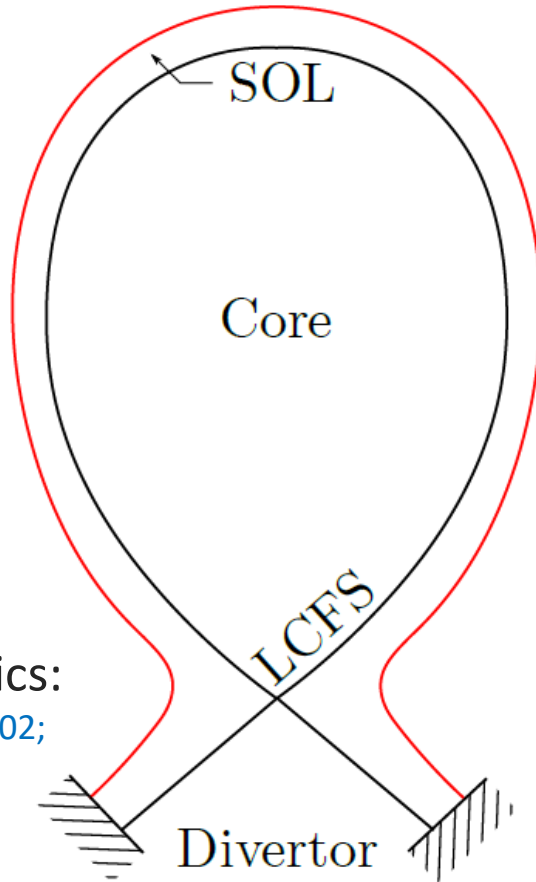
} Flux-driven,
semi-Lagrangian

Objective

Understanding (1D,1V) VOICE results from a fluid perspective:

Plasma self-organization under the **balance of sources, collisions** and **parallel transport losses** mediated at the plasma-wall Debye sheath

[Munsch 2024 a & b]



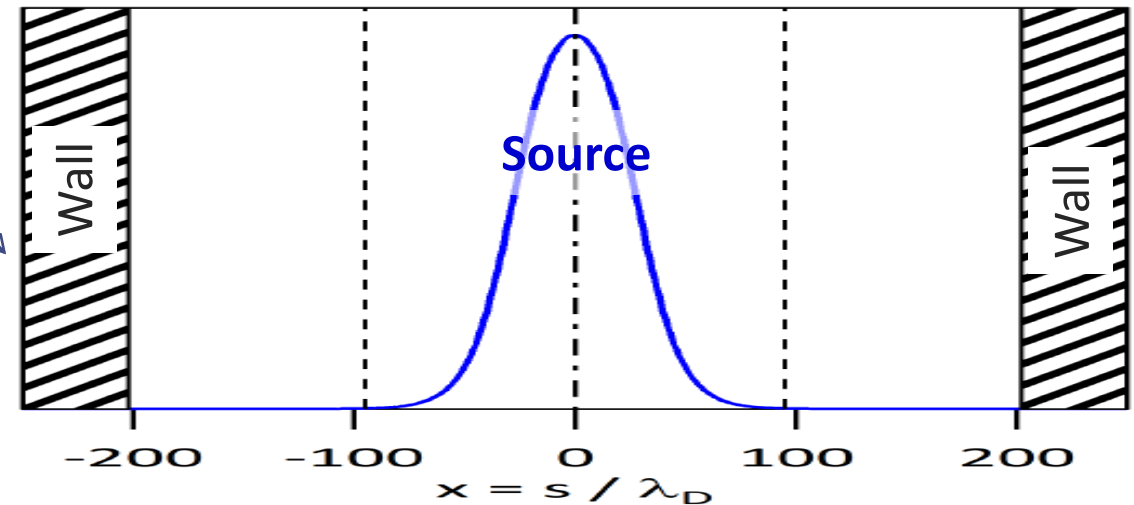
Refined sheath physics:

[Chodura 1982; Tskhakaya 2002; Geraldini 2018]

Review [Robertson 2013]

$$\left\{ \begin{array}{l} \partial_t f_a + \sqrt{A_a} (v_a \partial_x f_a - Z_a \partial_x \phi \partial_{v_a} f_a) = \mathcal{C}(f_a) + \mathcal{S}(f_a) \\ \partial_x^2 \phi = -\rho_c \quad \text{with} \quad \rho_c = \sum_{\text{species}} Z_a n_a. \end{array} \right.$$

Normal incidence – single ion species



Focus on numerical issues: semi-Lagrangian + non-equidistant mesh



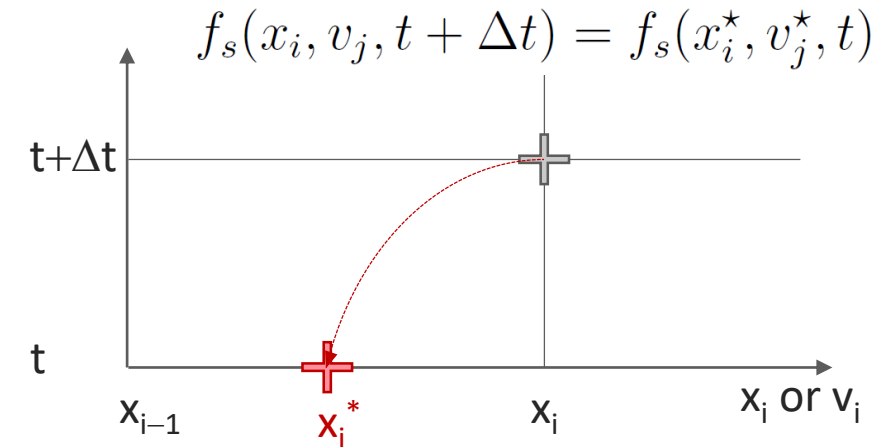
- ❑ **Strang splitting** → solve Vlasov advections & Source/Collisions separately [Cheng-Knorr 1976, Strang 1968]

$$\partial_t f_a + \sqrt{A_a} (v_a \partial_x f_a - Z_a \partial_x \phi \partial_{v_a} f_a) = \mathcal{C}(f_a) + \mathcal{S}(f_a)$$

- ❑ **Semi-Lagrangian scheme** [Staniforth 1991, Sonnendrücker 1999]

Vlasov $\Rightarrow f_s = \text{Cst}$ along trajectories

- Find **foot print** (x_i^*, v_i^*) of characteristics from (x_i, v_i)
- **Interpolation** (cubic splines) $\rightarrow f_s(x_i^*, v_i^*, t)$

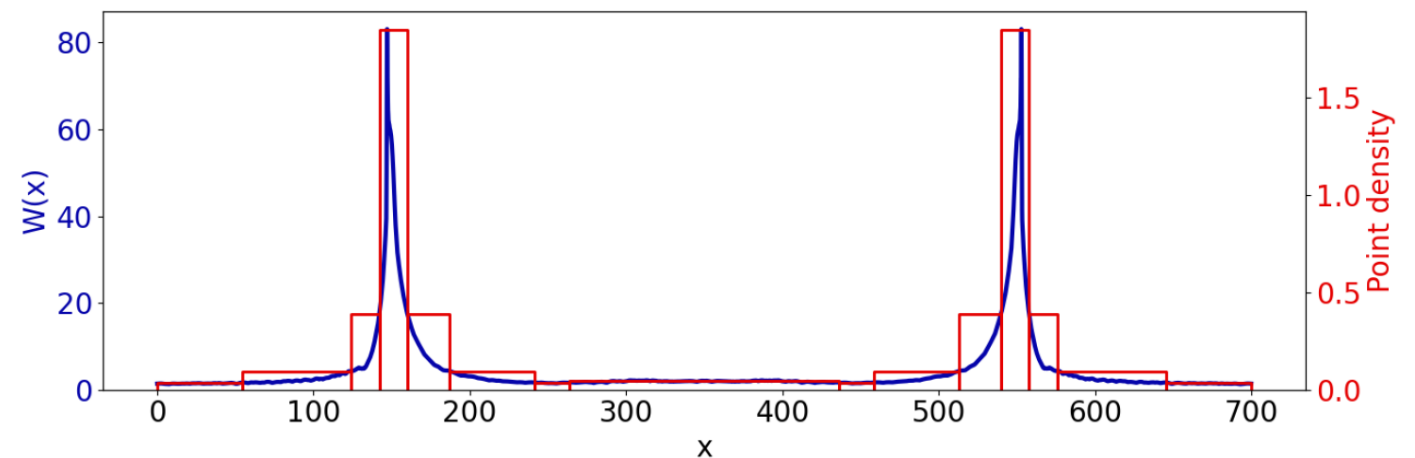


- ❑ **Refined mesh where strong gradient/curvature** [Bourne 2023]

Typical parameters:

$m_i/m_e = 400$	mass ratio
$L_x = 700\lambda_{D0}$	sim. box length
$N_x = 1500$	pts in x direction
$N_v = 700$	pts in v direction

~20h to reach steady state (NVIDIA Tesla V100, 5120 CUDA cores)



Focus on collision operator

$$\partial_t f_a + \sqrt{A_a} (v_a \partial_x f_a - Z_a \partial_x \phi \partial_{v_a} f_a) = \mathcal{C}(f_a) + \mathcal{S}(f_a)$$



Self collisions

$$C_{ss}(f_s) = \nu_{D0}^* \frac{\partial}{\partial v_s} \left\{ D_v f_{Ms} \frac{\partial}{\partial v_s} \left(\frac{f_s}{f_{Ms}} \right) \right\}$$

[Dif-Pradalier 2011, Estève 2015]

Magnitude

Velocity dependent diffusion coef. $\sim v^{-3}$

Maxwellian with space-time evolving N_{Ms} , U_{Ms} & T_{Ms} to conserve particles, momentum & energy

$$D_v = D_0 \frac{\Phi - G}{y_s} \quad \left| \quad \begin{aligned} \Phi(y_s) &= \frac{2}{\sqrt{\pi}} \int_0^{y_s} e^{-z^2} dz \\ G(y_s) &= \frac{\Phi - y_s \Phi'}{2y_s^2} \end{aligned} \right. \quad y_s = |v_s| / \sqrt{2T_s}$$

Inter species coll.

$$C_{ss'}(f_s) = \nu_{D0}^* \left\{ \frac{C_{\mathcal{E}}^{ss'}}{n_s T_s} \left(\frac{(v_s - u_s)^2}{T_s} - 1 \right) + \frac{C_{\Gamma}^{ss'}}{n_s T_s^{1/2}} \frac{v_s - u_s}{\sqrt{T_s}} \right\} F_{Ms}$$

$$C_{\mathcal{E}}^{ss'} = -3n_s \frac{m_s}{m_s + m_{s'}} \nu_{ss'} (T_s - T_{s'}) - u_s C_{\Gamma}^{ss'}$$

$$C_{\Gamma}^{ss'} = -n_s m_s \nu_{ss'} (u_s - u_{s'})$$

⇒ Simple fluid-like momentum & energy transfers

Focus on source/sink terms

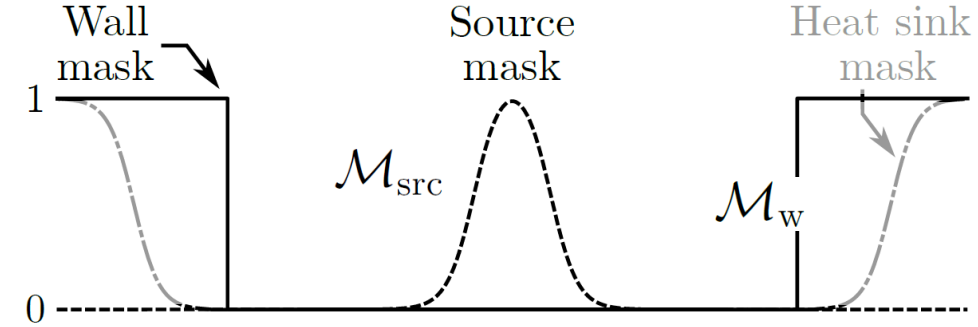
$$\partial_t f_a + \sqrt{A_a} (v_a \partial_x f_a - Z_a \partial_x \phi \partial_{v_a} f_a) = C(f_a) + \mathcal{S}(f_a)$$



normalization to $\lambda_{D0} = (\epsilon_0 T_0 / e^2 n_0)^{1/2}$, $v_{T0s} = (T_0 / m_s)^{1/2}$, $\omega_{p0s} = v_{T0s} / \lambda_{D0}$

Source of particles & heat (convective) [Sarazin 2011]

$$\mathcal{S}_{\text{src}}(f_s) = \underbrace{\frac{\mathcal{M}_{\text{src}}(x)}{\int_0^{L_x} \mathcal{M}_{\text{src}}(x) dx}}_{\text{Spatial shape}} \underbrace{\frac{s_k}{\sqrt{2\pi T_{\text{src}}/m_s}}}_{\text{Magnitude}} \exp\left(-\frac{m_s v_s^2}{2T_{\text{src}}}\right)$$

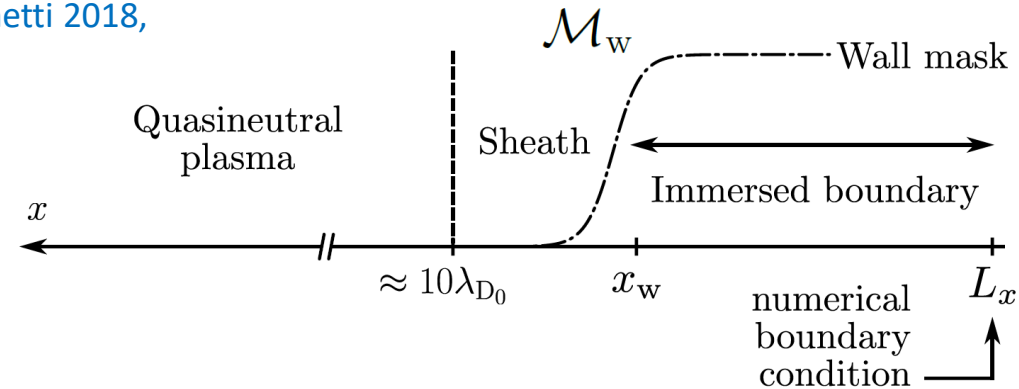


Sink = immersed boundary ("penalized wall")

[Paredes 2014, Baschetti 2018, Dif-Pradalier 2022]

$$\mathcal{S}_{\text{sink},n}(f_s) = -\mathcal{M}_w \nu_s (f_s - f_{ws})$$

$$f_{ws}(v) = \frac{n_w}{\sqrt{2\pi T_w/m_s}} \exp\left(-\frac{m_s v_s^2}{2T_w}\right) \quad \text{with } n_w \ll n_0$$

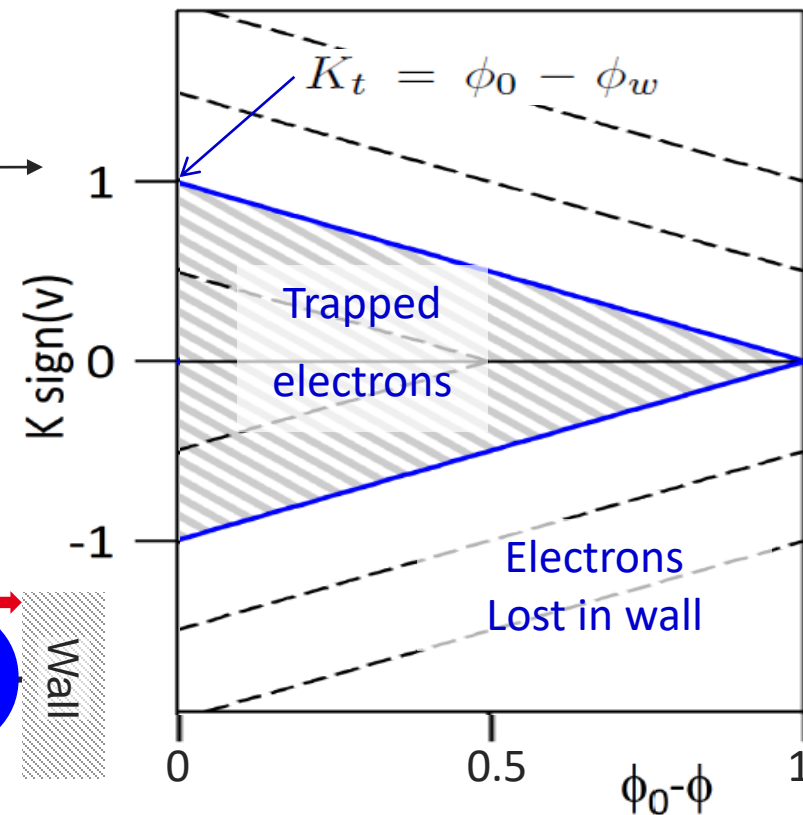
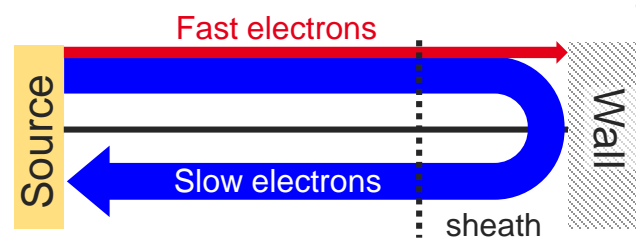
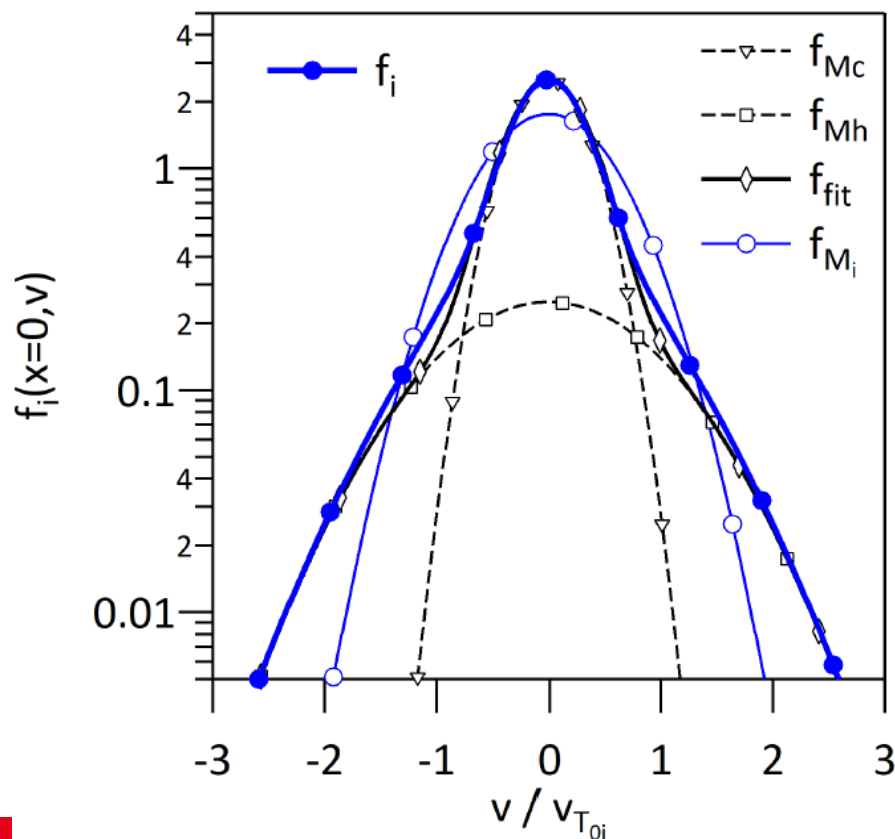


N.B.: \mathcal{M}_w does not precisely determine wall position x_w

Collisions mandatory to reach steady-state

- Electron energy conservation at vanishing source & without collisions:

$$K = \frac{1}{2}v^2 = K_0 - (\phi_0 - \phi)$$



- Source continuously injects trapped electrons
- W/o coll., trapped/lost regions are decoupled
 \Rightarrow collisions mandatory

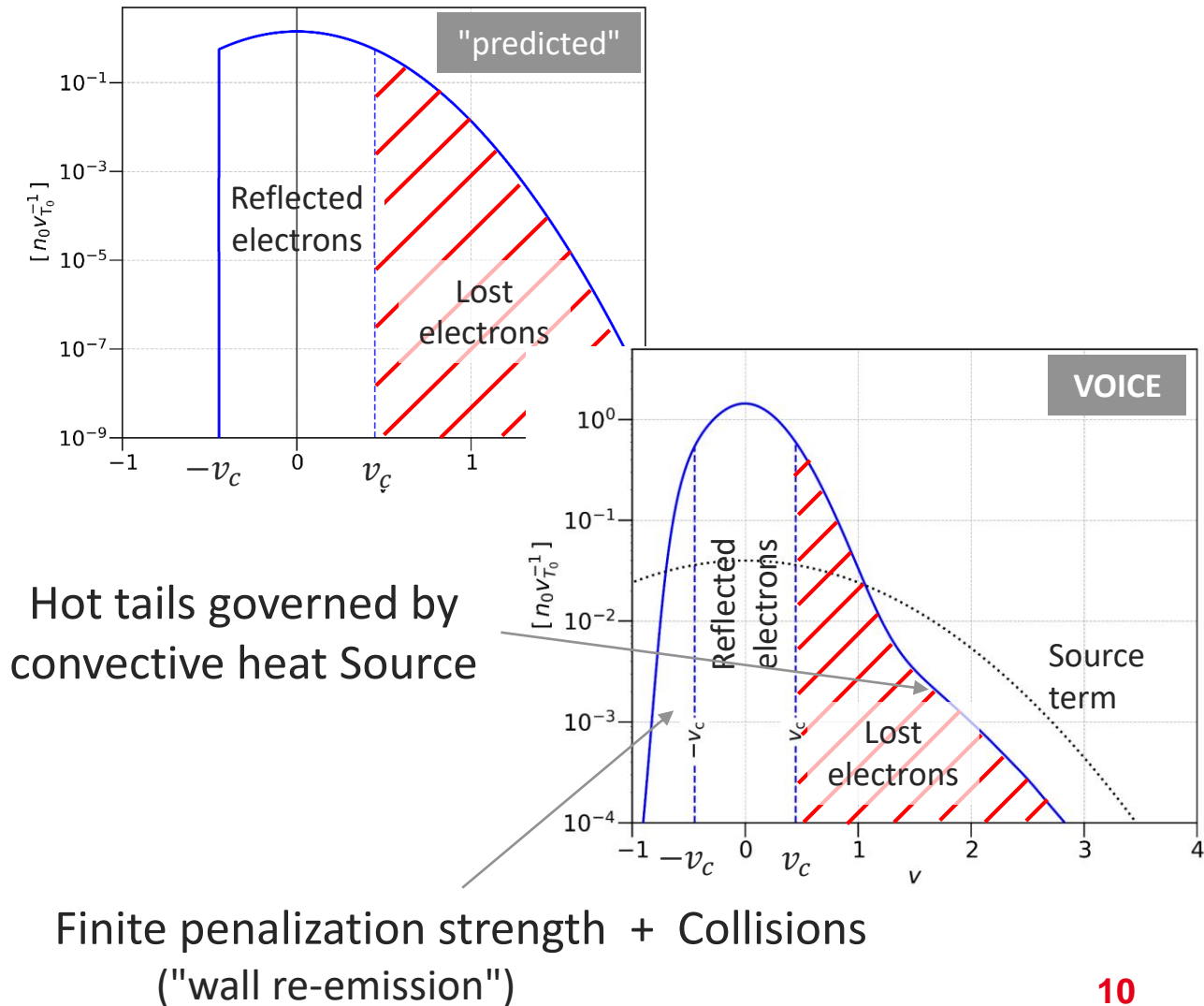
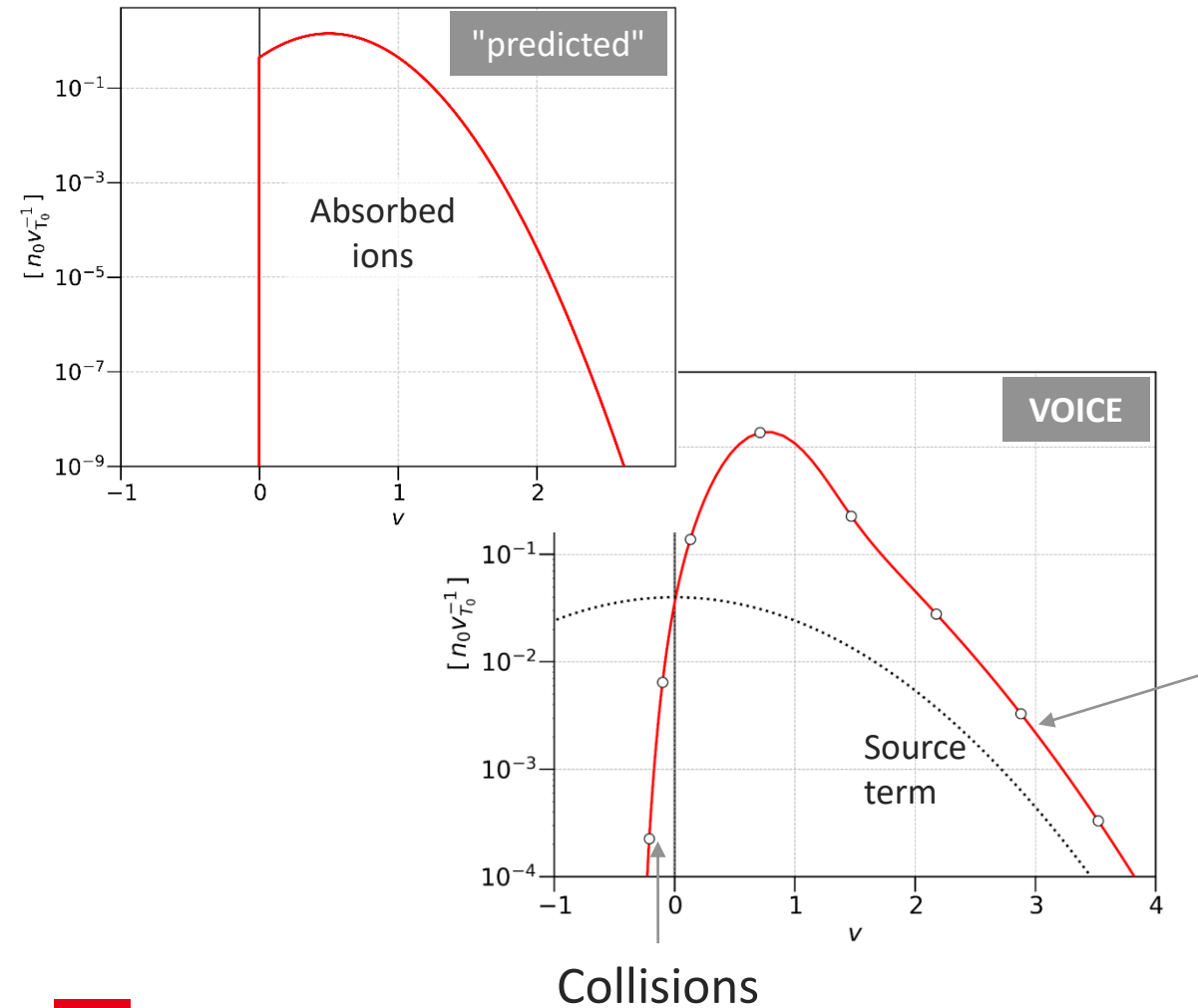
[Boyd 1951;
Persson 1962]

Distribution functions @ sheath entrance \neq truncated Maxwellians

Plasma **self-organization** under the combined effects of **source**, **collisions** and **Debye sheath**

Ions: "forbidden" region populated by collisions

Electrons: collisions + incomplete wall absorption



Hot tails governed by convective heat Source

Recovery of potential drop & its expected dependencies

- Potential drop in the sheath $\Delta\phi_{sh}$ governed by different electron-ion inertia

$$\Delta\phi_{sh}^{pred.} = \frac{T_e^{sh}}{e} \log\left(\frac{\Gamma_i^{sh}}{\Gamma_e^{sh+}}\right) = \frac{T_e^{sh}}{2e} \log\left(\underbrace{2\pi \frac{m_e}{m_i} M^2 \left(1 + \frac{T_i^{sh}}{T_e^{sh}}\right)}_{2\Lambda \approx 2 \times 3.8}\right)$$

- Recovered with VOICE provided one accounts for "outgoing" electrons Γ_e^-

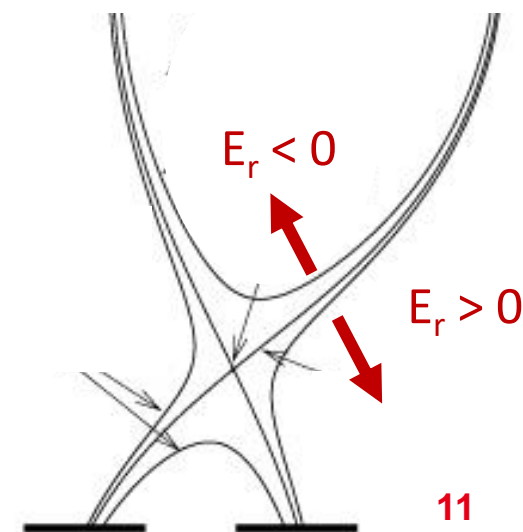
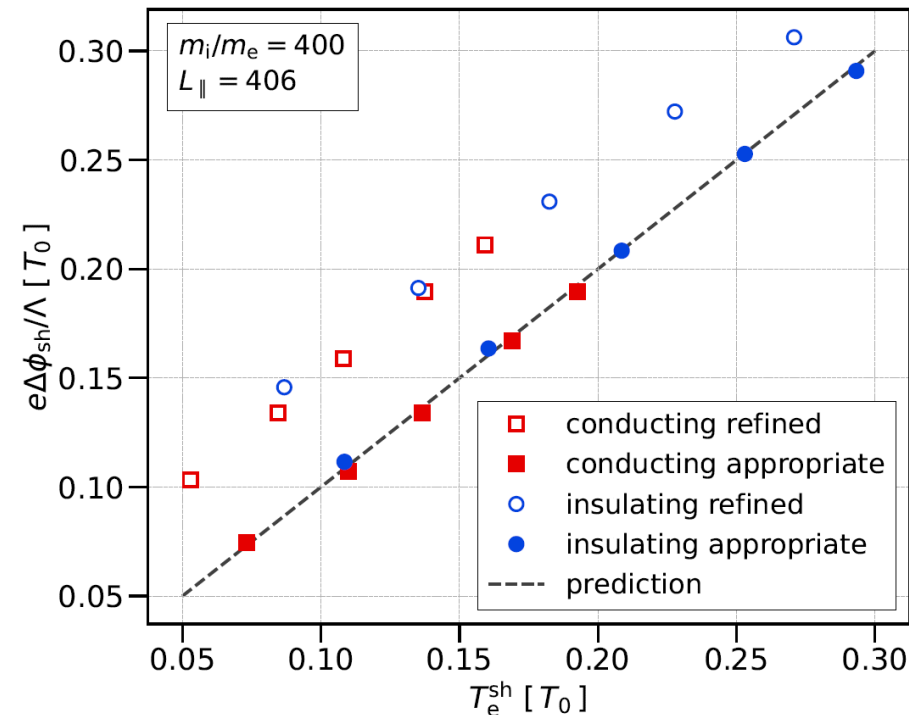
$$\Rightarrow \Gamma_i^{sh} = \Gamma_e^{+pred.} - \Gamma_e^- \quad \text{With } \Gamma_e^{+pred.} = \int_{v_c}^{+\infty} dv v n_e^{sh} \sqrt{\frac{m_e}{2\pi T_e^{sh}}} e^{-\frac{m_e v^2}{2T_e^{sh}}}$$

So that

$$\Delta\phi_{sh}^{pred., ref.} = \frac{T_e^{sh}}{e} \log\left(\sqrt{2\pi \frac{m_e}{m_i} M^2 \left(1 + \frac{T_i^{sh}}{T_e^{sh}}\right)} \left(1 + \frac{\Gamma_e^-}{\Gamma_i^{sh}}\right)\right)$$

- Important consequence for fusion plasmas:

Radial electric field positive in the Scrape-Off Layer (SOL) $E_r^{SOL} \approx -\frac{\Lambda}{e} \nabla_r T_e > 0$



Bohm criterion: depends on – not well defined – sound speed

Fluid prediction for plasma-wall interaction:

Bohm criterion: $M = u_i/c_s \geq 1$ at sheath entrance

⇒ supersonic ion flow in Debye sheath

Expression of c_s depends on fluid closure

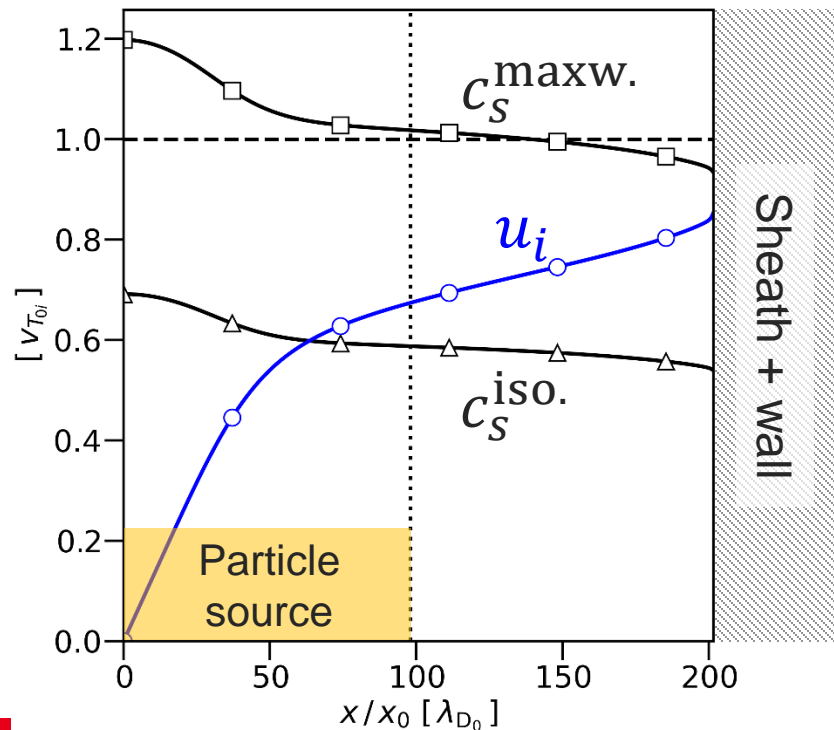
From Fourier transform of fluid equations → dispersion relation for c_s

Closure	Isothermal	Maxwellian	Cold ions	Polytropic
Sound speed c_s	$\sqrt{\frac{T_i + T_e}{m_i}}$	$\sqrt{\frac{3(T_i + T_e)}{m_i}}$	$\sqrt{\frac{T_e}{m_i}}$	$\sqrt{\frac{\gamma_p(T_i + T_e)}{m_i}}$
Assumptions	$T_s = \text{cte.}$	$Q_s^{\text{heat}} = 0$	$T_i = 0$	$\frac{dp}{p} = \gamma_p \frac{dn}{n}$

$$Q_s^{\text{heat}} = \int_{-\infty}^{+\infty} dv \frac{1}{2} m_s (v - u_s)^3 f_s$$

VOICE results: $Q_s^{\text{heat}} \neq 0$

Bohm criterion $M = \pm 1$ is not operational to define Debye sheath entrance



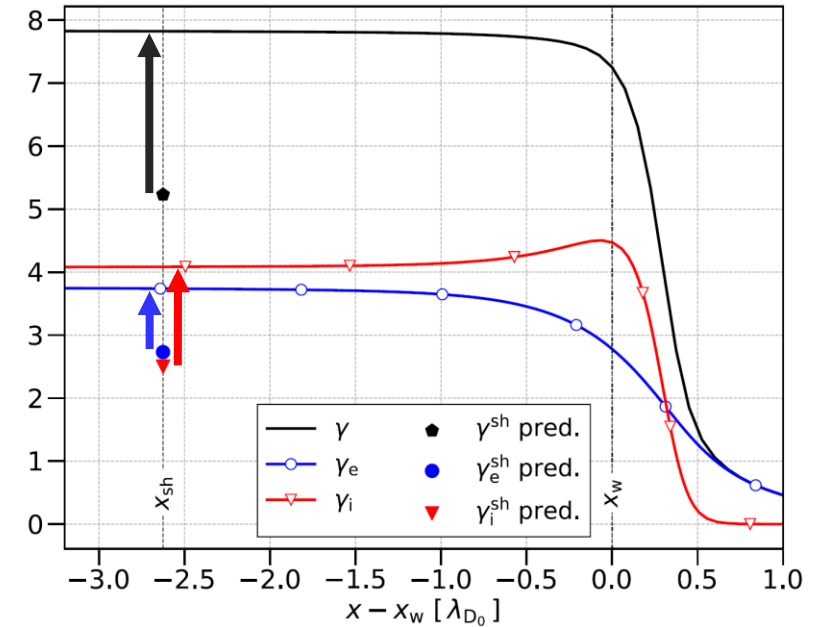
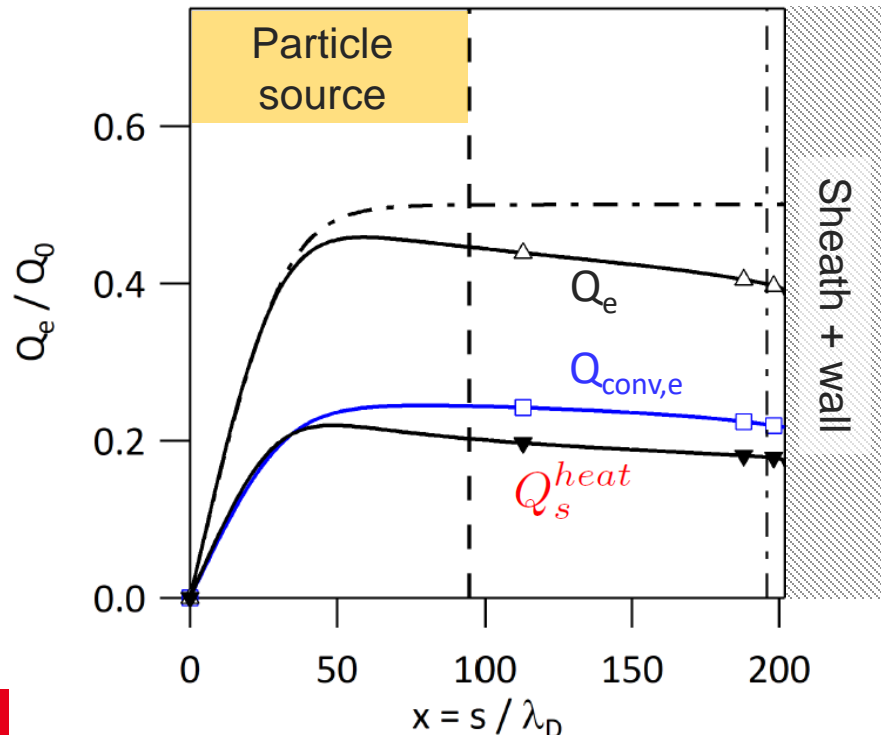
Larger sheath *heat transmission factors* than predicted

Total energy flux expressed as a function of convected flux:

$$Q_s = \gamma_s \Gamma_{sh} T_s$$

↑
Heat transmission factor

- ❑ Fluid framework (Maxw. closure) → Prediction for γ_s
- ❑ **VOICE results: larger γ_i (~60%) and γ_e (~35%)**



- ❑ Kinetic results:
 - **Non vanishing heat flux** (not predicted in fluid)

$$Q_s = \underbrace{u_s \left(\frac{3}{2} n_s T_s + \frac{1}{2} m_s n_s u_s^2 \right)}_{Q_{conv,e}} + Q_s^{heat}$$

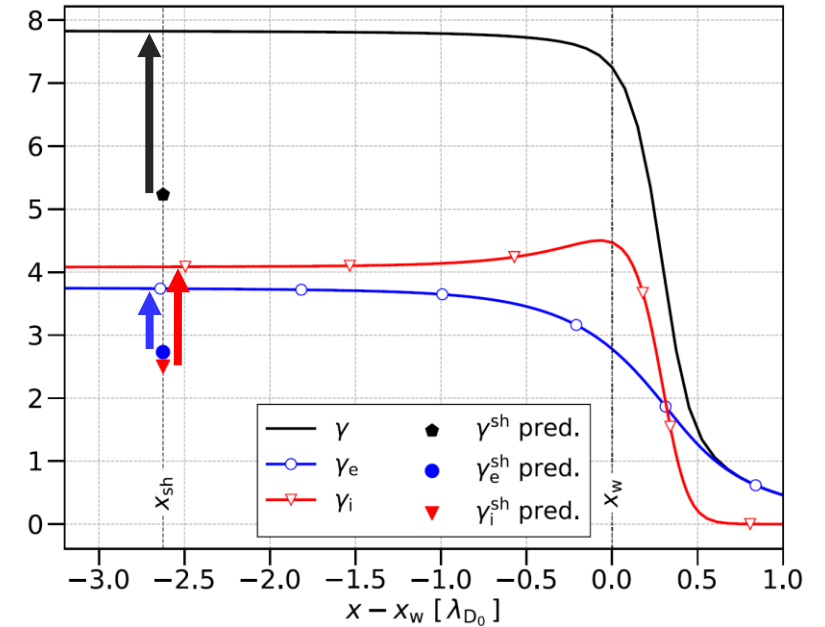
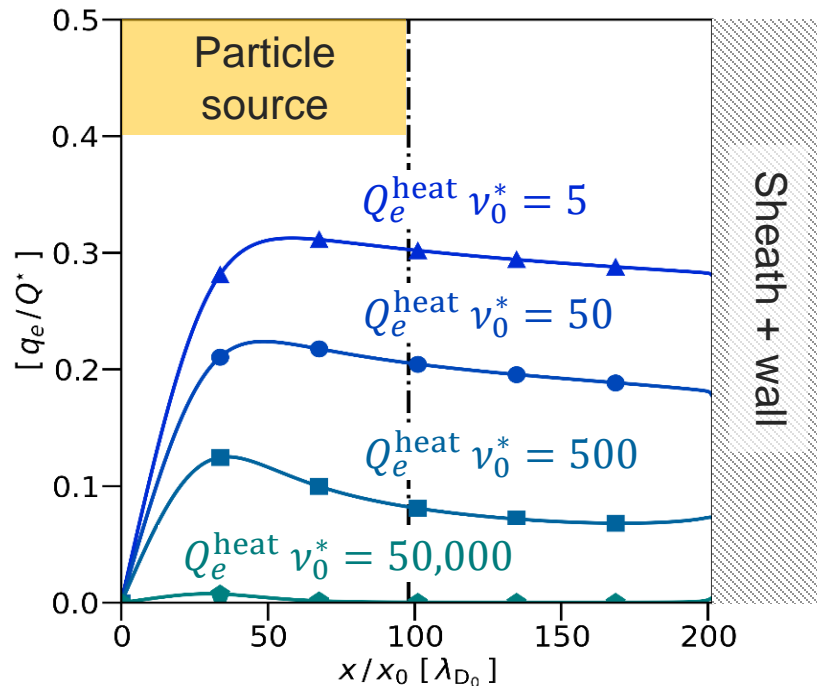
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- Extremely slow convergence of Q_s^{heat} towards 0 when $v_0^* \uparrow$

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3. Towards the **implementation of plasma-wall interaction in 5D gyrokinetics (GYSELA)**

VOICE = (1D,1V) – fully kinetic electrons & ions – Poisson

GYSELA = (3D,2V) – GK ions, DK electrons – Quasi-Neutrality

} Flux-driven,
semi-Lagrangian

Accounting for a source of neutrals

■ Motivations

- Plasma-wall interaction: particles recycled by the wall as neutrals at a rate > 99% in W environment
- SOL turbulent dynamics mostly governed by convection
- Flux-driven GK simulations with kinetic electrons require a particle source

■ Physics of the plasma-neutral interaction

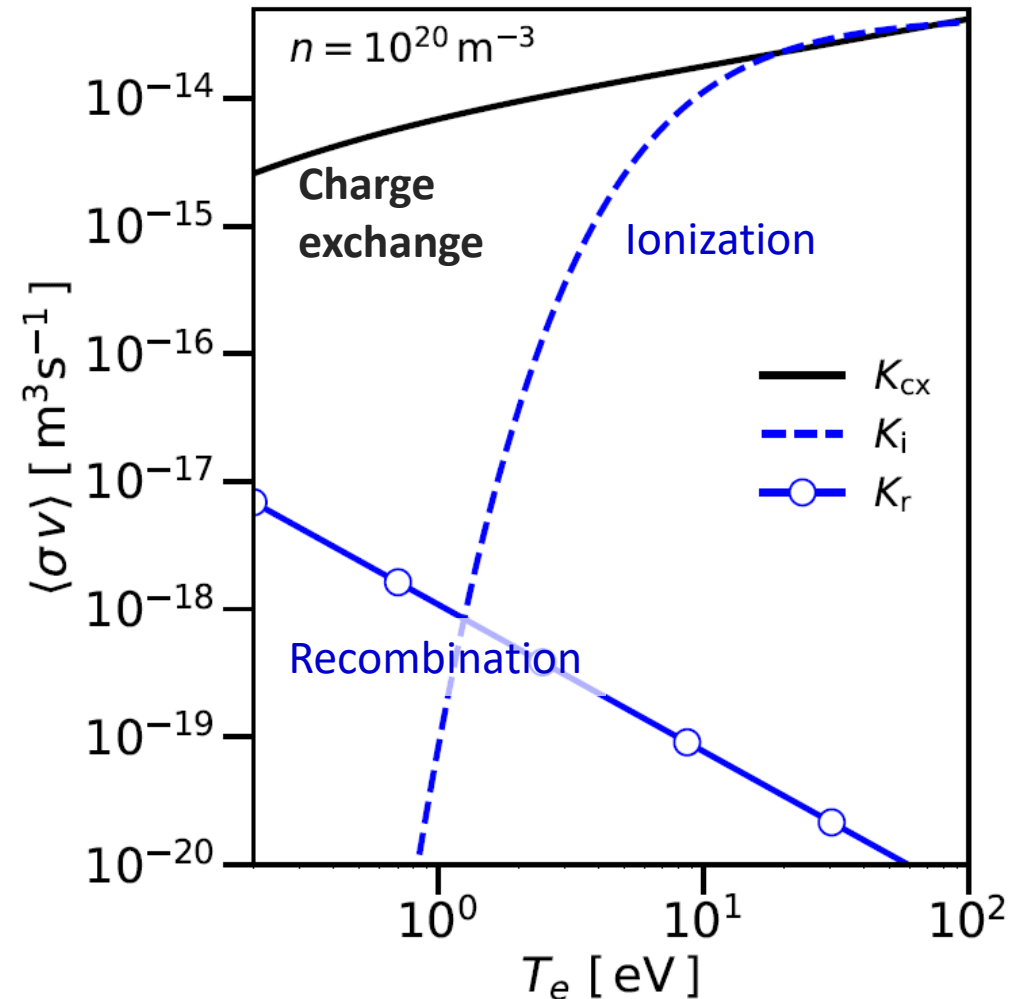
- Considered reactions: **charge-exchange**, **ionization** & **recombination**

▮ $\langle \sigma v \rangle_i$ strongly increases from 1 to 10eV \Rightarrow threshold

▮ $\langle \sigma v \rangle_r$ only relevant below $T \approx 1$ eV

- **Particle** source/sink $\rightarrow \langle \sigma v \rangle_i$ & $\langle \sigma v \rangle_r$
- **Momentum** & **Energy** transfers $\rightarrow \langle \sigma v \rangle_{cx}$, $\langle \sigma v \rangle_i$ & $\langle \sigma v \rangle_r$

[ADAS Database; J. Blanco 2024]



Neutrals modelled as a fluid → coupling to kinetic plasma species

■ Neutral-plasma coupling via source terms

- So far, source/sink restricted to particles (ioniz. + recomb.)
- Constraint: ensure proper balance "1 neutral ↔ 1 ion + 1 electron"

■ General method: projection on Hermite (& Laguerre) polynomials

[Sarazin 2011]

- $\mathcal{S}_v(v_a) = \sum_{h=0}^{+\infty} c_h H_h \left(\frac{v_a}{\sqrt{2T_{sc}}} \right) e^{-\frac{v_a^2}{2T_{sc}}} \rightarrow$ Fluid moments related to c_h coefficients

- Pure Sca of particles: $\mathcal{S}_n(v_a) = c_0 \left(\frac{3}{2} - \frac{v_a^2}{2T_{sc}} \right) e^{-\frac{v_a^2}{2T_{sc}}}$ with $\left\{ \begin{array}{l} c_0 = \frac{S_{n,N}}{\sqrt{2\pi T_{sc}}} \\ S_{n,N} = n_N n_e \langle \sigma v \rangle_i - n_i n_e \langle \sigma v \rangle_r \end{array} \right.$

$$\left[\int_{-\infty}^{+\infty} dv_a \mathcal{S}_n(v_a) = \sqrt{2T_{sc}} \sum_h \langle H_0, c_h H_h \rangle = \sqrt{2\pi T_{sc}} c_0 = S_{n,N} \quad \langle f, g \rangle = \int_{-\infty}^{+\infty} f(y)g(y)e^{-y^2} dy \right]$$

■ Conservation equations:

$$\left\{ \begin{array}{l} \frac{df_a}{dt} = \mathcal{C}(f_a) + \mathcal{S}_n(v_a) \\ \partial_t n_N + \nabla \cdot \Gamma_N = -S_{n,N} \end{array} \right.$$

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Plasma-wall interaction in the GK framework: main issues



■ Debye sheath physics

- Non-neutral plasma →
- Strong parallel electric field on a few λ_D →

GK physics

violates usual GK assumption
subgrid w.r.t. typical scales $L_{\parallel} \approx L_s/k_{\theta}\rho_s$

■ Main objectives / challenges

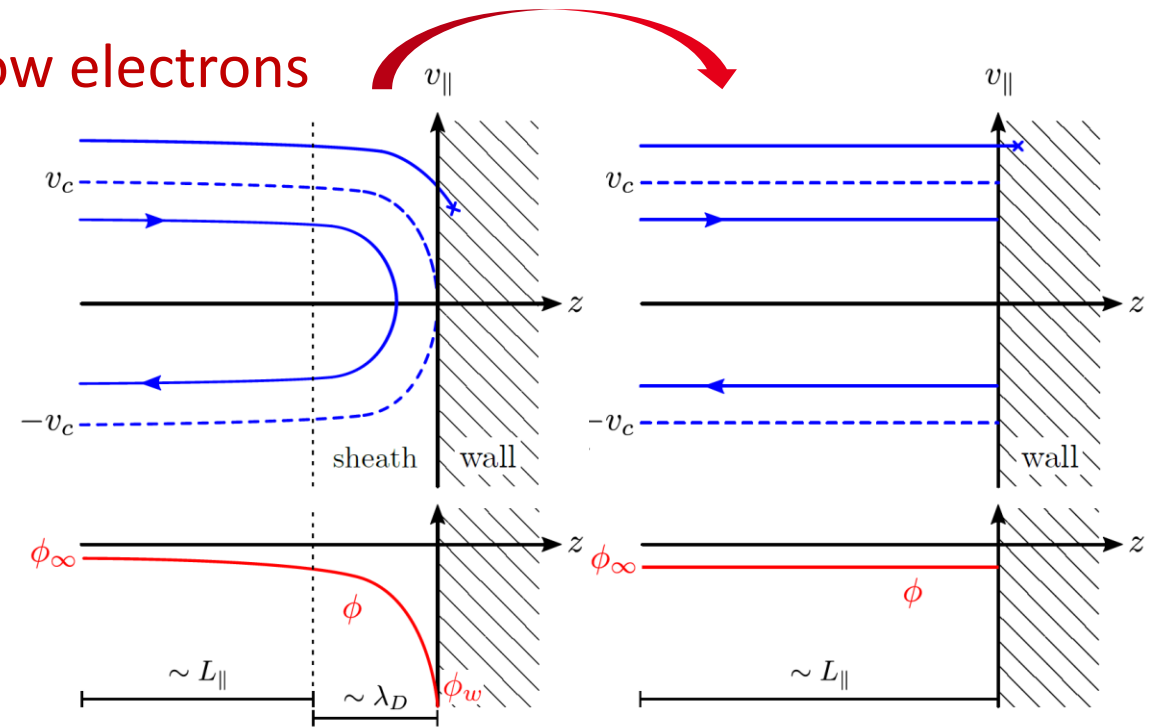
- Keep the plasma quasi-neutral ($k\lambda_D \ll 1$)
- Recover linear dependency of ϕ with T_e
- Ensure absorption of all ions & reflection of slow electrons

OK with adiabatic electrons [Caschera 2018, Dif-Pradalier 2022]

■ State-of-the-art

- Logical sheath
- Conducting sheath
- New model: "flux-averaged sheath"

adapted to semi-Lagrangian full-f



Constraining the cut-off velocity $v_c = \sqrt{(2e \Delta\phi/m_e)}$

(I)

Electrons with $|v_{//}| \leq v_c$ are reflected back

→ different strategies to estimate $v_c(\Delta\phi)$

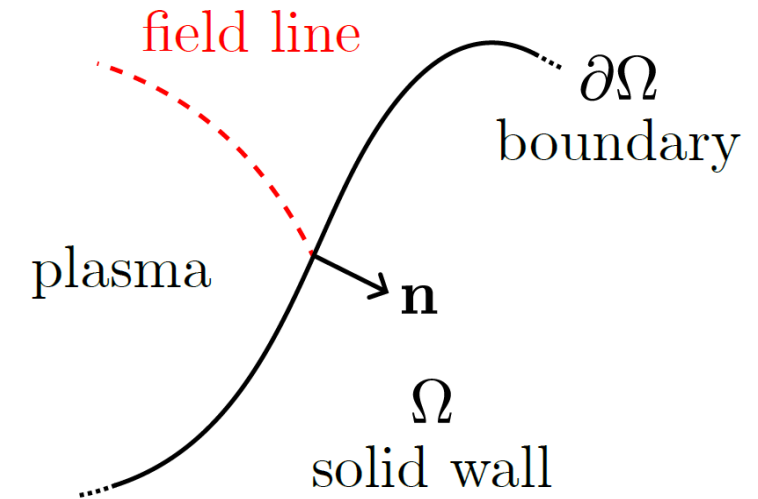
■ Logical sheath (initially developed for PIC codes): [Parker 1993]

enforces $\mathbf{j}=\mathbf{0}$ at each time/position on $\partial\Omega$

- At each time, count the N_i ions crossing $\partial\Omega$
- Remove the N_i fastest electrons → v_c is the velocity of the fastest reflected electron

■ Conducting sheath: allows for finite local currents on $\partial\Omega$ [Shi 2015]

- GK quasi-neutrality $\nabla_{\perp}^2\phi = \rho \rightarrow \phi$ at any position on $\partial\Omega$
- $v_c = \sqrt{(2e \Delta\phi/m_e)}$ defines the velocity of the slowest absorbed electron



Constraining the cut-off velocity $v_c = \sqrt{(2e \Delta\phi/m_e)}$

(II)

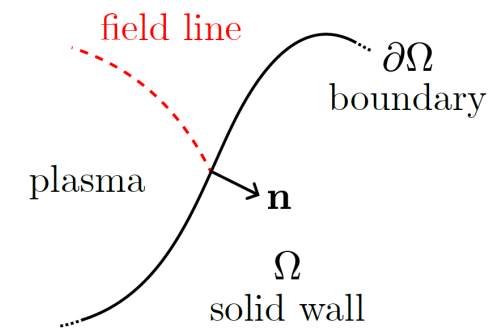


Electrons with $|v_{||}| \leq v_c$ are reflected back

→ different strategies to estimate $v_c(\Delta\phi)$

■ "Flux-averaged sheath":

[Munsch 2024 c]



- Enforces *vanishing current on average over $\partial\Omega$* → allows for **finite local currents**

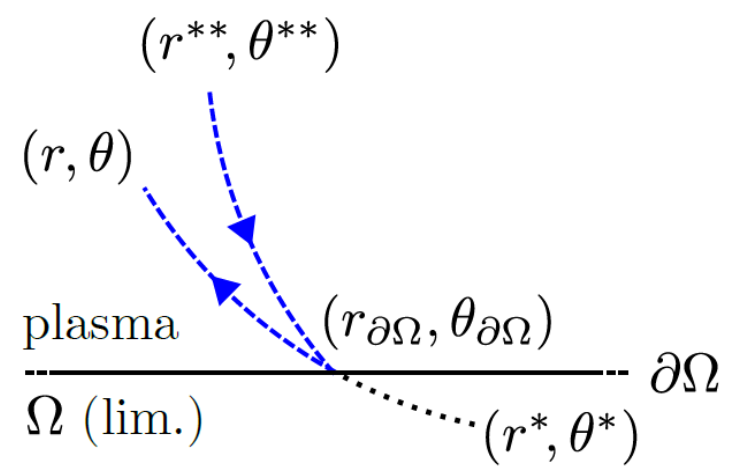
- v_c implicitly defined by

$$\langle \Gamma_i^{\partial\Omega}(\mathbf{x}, t) \rangle_{\partial\Omega} = \langle \bar{\Gamma}_e^{\partial\Omega}(\mathbf{x}, v_c, t) \rangle_{\partial\Omega}$$

$$\approx \frac{\mathbf{B}}{B} \approx \frac{\mathbf{E} \times \mathbf{B}}{B^2} \approx \frac{m_s v_{||}^2 + \mu B}{e_s B} \frac{\mathbf{B} \times \nabla B}{B^2}$$

$$\int_{\partial\Omega} d^2S \int_{-\infty}^{+\infty} dv_{||} \int_0^{+\infty} d\mu J_v J_0 F_i(\mathbf{x}, v_{||}, \mu) (v_{||} \mathbf{b}_{||}^* + \mathbf{v}_E + \mathbf{v}_D) \cdot \mathbf{n} = \int_{\partial\Omega} d^2S \int_{-v_c}^{+\infty} d\bar{v}_{||} \int_0^{+\infty} d\mu J_v F_e(\mathbf{x}, \bar{v}_{||}, \mu) (\bar{v}_{||} \mathbf{b}_{||}^* + \mathbf{v}_E + \mathbf{v}_D) \cdot \mathbf{n}$$

- All **crossing ions are absorbed** (penalization)
- Slow electrons are reflected back** into the plasma



N.B.: additional complexity arising from backward semi-Lagrangian scheme



Plasma-wall boundary: ions absorbed & electrons reflected

Simulations w/o quasi-neutrality → successful check of ion & electron dynamics

■ Ions absorbed within the limiter

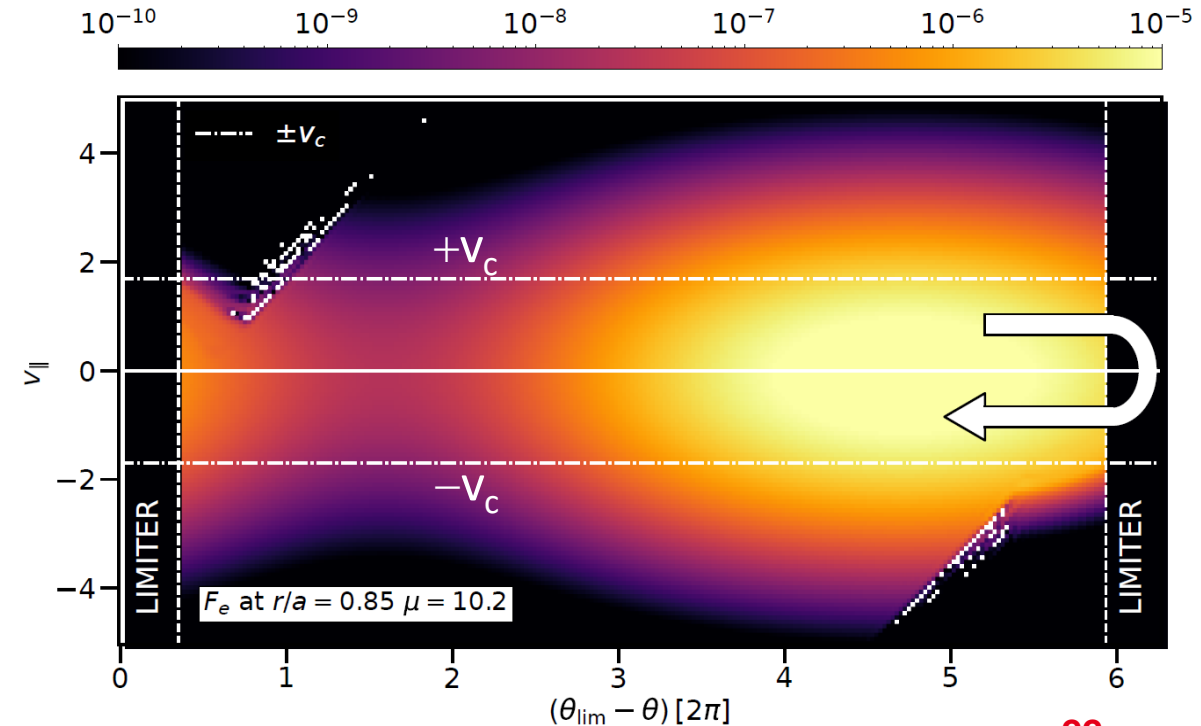
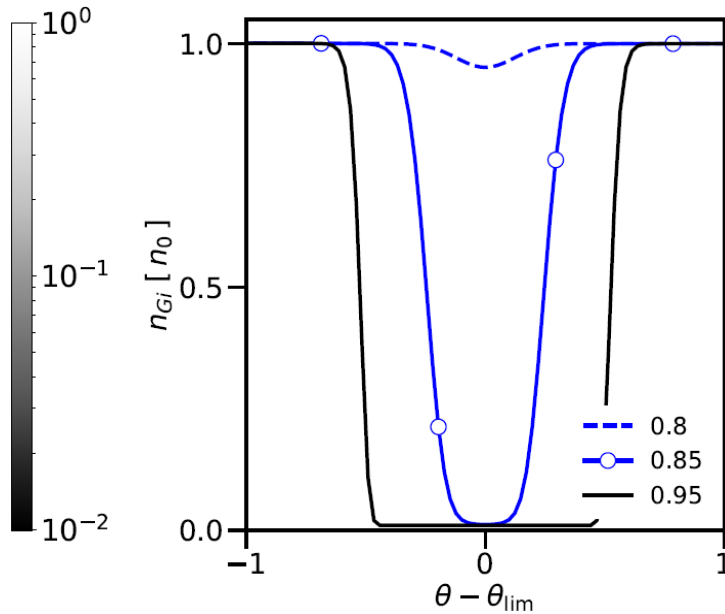
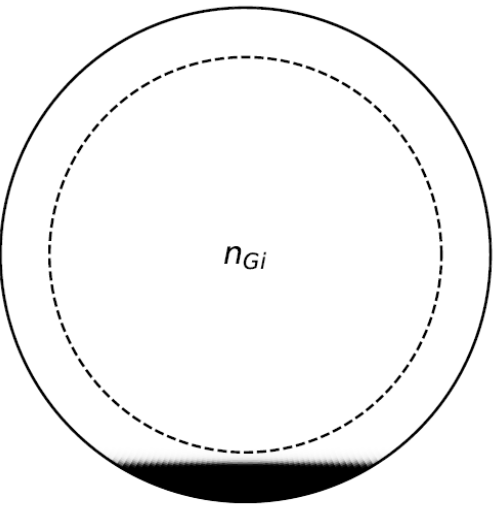
via penalization → **mask** M_{lim}

$$dF_i/dt = \dots - \nu (F_i - F_{lim}) M_{lim}$$

■ Electrons reflected back at the cut-off velocity v_c

Depletion front propagates along θ away from limiter / into the plasma

----- $\rho_{sep} = 0.8$



Plasma-wall boundary: ions absorbed & electrons reflected

Simulations w/o quasi-neutrality → successful check of ion & electron dynamics

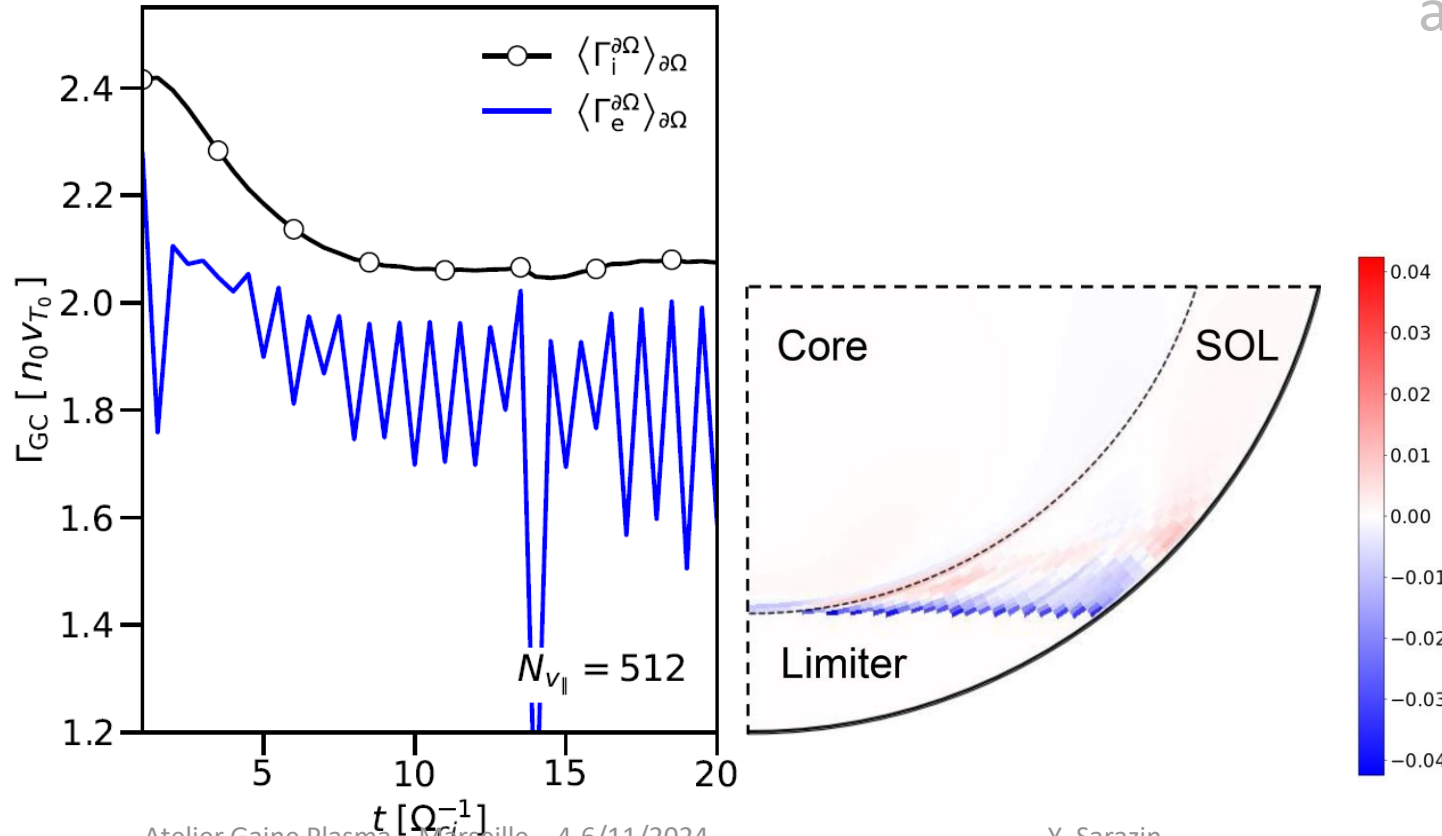
Ions absorbed within the limiter

via penalization → mask M_{lim}

$$dF_i/dt = \dots - v (F_i - F_{lim}) M_{lim}$$

Electrons reflected back at the cut-off velocity v_c

Depletion front propagates along θ away from limiter / into the plasma



Current issue with QN:

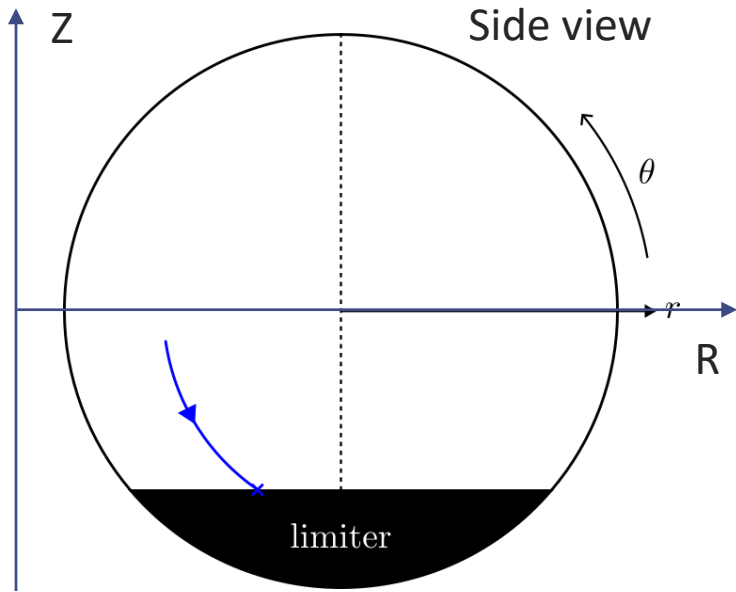
Charge density build-up close to limiter due to imbalance between ion & electron particle fluxes



Thin toroidal limiter = "simple" alternative Boundary Condition



Axisymmetric limiter



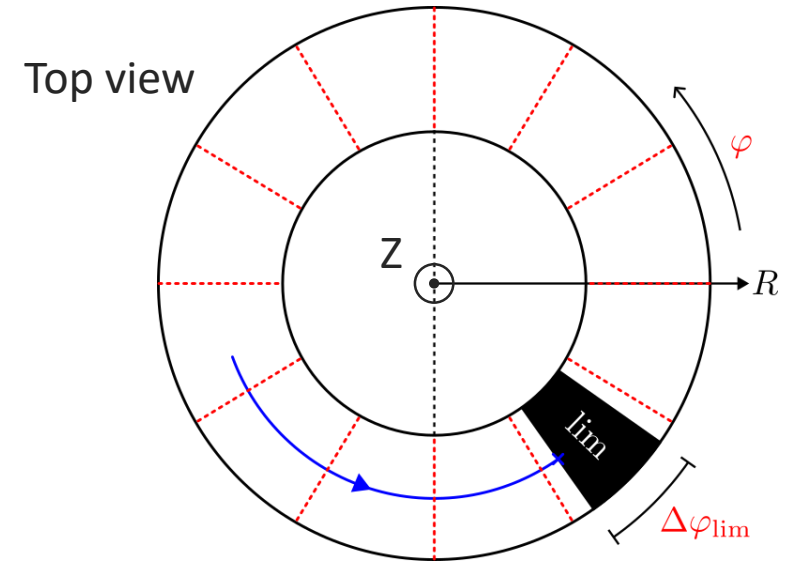
Particles intercept **axisymmetric** limiter during (r, θ) advection

⇒ immersed in Vlasov
and Quasi-Neutrality

Strang splitting
→ separate advections
in (r, θ) and φ

1. v_{\parallel} advection on $\Delta t/2$
2. φ advection on $\Delta t/2$
3. (r, θ) advection on Δt
4. φ advection on $\Delta t/2$
5. v_{\parallel} advection on $\Delta t/2$

Thin limiter located in between two toroidal mesh points

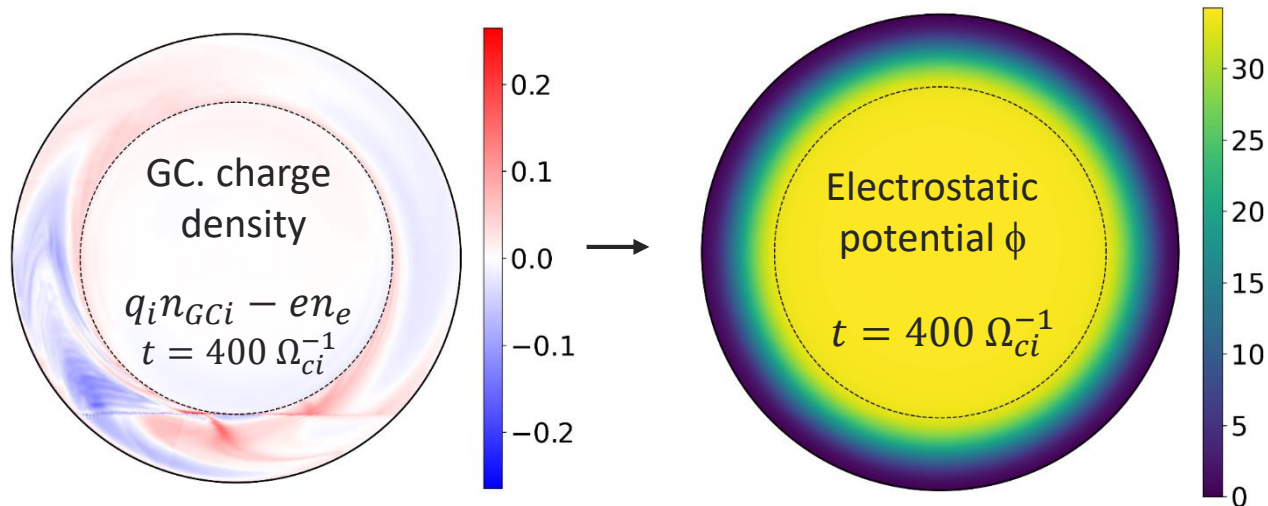
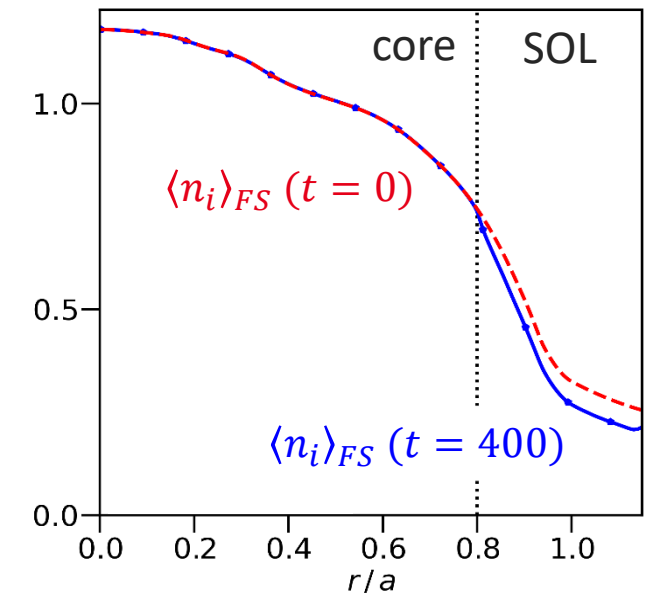


Particles intercept **thin** limiter during φ advection

⇒ immersed in **Vlasov only**
(not in Quasi-Neutrality)

Thin toroidal limiter → depletion of SOL density at early times

- Thin limiter → longer ($\sim \times 10$) simulations w.r.t. axi-symmetric limiter
- Large charge density at early times: $\phi \approx \langle \phi \rangle_{FS} \gg 1$ in simulation
 \Rightarrow Necessity to modify quasi-neutrality & radial Boundary Condition



Dirichlet radial Boundary Condition:

$$\phi(r=r_{\max}) = 0$$



Translates into $v_c = 0$

\Rightarrow no electron reflected

Conclusions

■ Kinetic Debye sheath (VOICE)

- Immersed boundaries (penalization) OK to recover main physics
- Collisions mandatory → allow for steady-state – non "ideal" distribution functions
- C_s loosely defined ⇒ Bohm criterion not operational (→ Debye sheath where ρ shoots-up)
- Kinetic self-organization → finite ion & electron heat fluxes ⇒ large sheath heat transmission factors

■ Neutrals as a fluid (VOICE → Gysela-X)

- Fluid model successfully coupled to kinetic plasma
- Next steps: Add momentum & energy exchanges

Account for recycling coefficients (> 99% for particles in W environment) → $S_{n,N} \propto \Gamma_i^{\partial\Omega}$

From 1D to 3D → implement in Gysela-X

■ Consistent plasma-wall interplay within Gyro-Kinetic description (GYSELA)

- Subgrid modelling of Debye sheath is challenging
- Absorption of ions & reflection of slow electrons OK in GYSELA
- New "Flux-averaged sheath" model – current issue (flux imbalance) under investigation
- Promising alternative: toroidally localized limiter → requires adjustments

Associated publications



VOICE results

E. Bourne et al., *Non-uniform splines for semi-Lagrangian kinetic simulations of the plasma sheath*

J. Comput. Phys. 488 (2023) 112229

Y. Munschy (a) et al., *Kinetic plasma-wall interaction using immersed boundary conditions*

Nucl. Fusion 64 (2024) 056027

Y. Munschy (b) et al., *Kinetic plasma-sheath self-organization*

Nucl. Fusion 64 (2024) 046013

GYSELA results

E. Caschera et al., *Immersed boundary conditions in global, flux-driven, gyrokinetic simulations*

J. Phys. Conf. Series 1125 (2018) 012006

G. Dif-Pradalier et al., *Transport barrier onset and edge turbulence shortfall in fusion plasmas*

Commun. Phys. 5 (2022) 259

Y. Munschy (c), *Kinetic and Gyrokinetic physics of plasma-wall interaction in tokamaks*

PhD thesis, Aix-Marseille Univ. (2024)